

volumetric/topographical representation. These images can be presented in a selected sequence to provide an animation of body B. In one form, a sequence of about 32 to about 64 generally evenly spaced views about axis R are used to generate a rotating animation of body B about axis R.

From operation 166, procedure 120 continues with operation 168. In operation 168, one or more measurement indicators are also displayed that overlay one or more body images. In one embodiment, the displayed image of a person can be adjusted to hide/conceal body features to which a privacy objection might be made. Alternatively, the rendering can include a schematic body image similar to a mannequin in appearance.

Alternatively or additionally, the volumetric/topographical representation of body B can be displayed as a number of sectional images. FIG. 6 presents computer-generated images determined from an experiment that was performed using an arrangement to simulate system 20. Image 320 corresponds to a front viewing angle of a clothed person; where the person's clothing is generally transparent to the interrogating electromagnetic radiation. For image 320, indicator lines 330a, 330b, 330c, 330d, and 330e correspond to various sectional views 340 that are more specifically designated head sectional view 340a, chest sectional view 340b, stomach sectional view 340c, thigh sectional view 340d, and knee sectional view 340e; respectively. Image 320 and sectional views 340 were determined from a volumetric/topographical representation obtained in accordance with procedure 120 using an ultrawide sweep range of 24 GHz to 40 GHz for each activation of an array element. Eight arc segments S were processed for this experiment in an arrangement like that represented in FIG. 5. It should be appreciated that this topographic representation defines a number of different circumferences of the depicted body, such as those represented by sectional views 340. In still other embodiments, display of body images may be absent. Alternatively or additionally, the information gathered with subsystem 40 is sent via computer network 64 to one or more remote sites 80. Sites 80 can perform some or all of the data processing represented by operations 160, 162, 164, 166, and/or 168 in lieu of processor(s) 44. In one process, a clothed individual is nonintrusively scanned by booth 30 and the measurement(s), image(s), animation, and/or topographical information of the individual's body is sent via server 63 and network 64 to a designated computer 82. From this computer 82, the measurement information can be sent via network 64 to one or more e-commerce clothing suppliers or other clothing business to electronically order or manufacture clothing of the desired size and style. Alternatively or additionally, the topographical information can be used to automatically generate by computer or otherwise custom two-dimensional (2-D) patterns for apparel manufacture.

For procedure 120, transceiver 42 and processor(s) 44 include logic to perform the various operations described. This logic can be in the form of software programming instructions, firmware, and/or of a hardwired form, just to name a few. Furthermore such logic can be in the form of one or more signals carried by, on, or with memory 46, R.M.D. 48, and/or one or more parts of computer network 70. In one example, logic signals to perform one or more operations is transmitted to or from processor(s) 44 via network 70. Alternatively or additionally, programming for processor(s) 44 is transported or disseminated through R.M.D. 48 and/or one or more other storage devices.

FIG. 7 illustrates interrogation system 420 of another embodiment of the present invention. System 420 illumi-

nates body B with selected electromagnetic radiation in the manner described in connection with system 20. For system 420, body B is in the form of person 422 wearing clothing articles 424a and 424b. As in previously described embodiments, system 420 can be used to interrogate inanimate objects as well.

System 420 includes scanning booth 430 coupled to control and processing subsystem 440. Scanning booth 430 includes stationary platform 432 arranged to support body B and frame 433 to support motor 434 coupled to array 436. In contrast to the platform rotation of booth 30, scanning booth 430 selectively rotates array 436 about rotational axis R and platform 432 during interrogation. For this arrangement, array 436 follows a generally circular pathway to provide a corresponding imaginary cylinder about platform 432. In one form suitable for scanning a person in the standing position, the radius of this cylinder is about 1 meter. Array 436 is otherwise configured the same as array 36.

In system 420, subsystem 440 is configured the same as subsystem 40 of system 20 and is likewise arranged to perform procedure 120. However, during the performance of procedure 120, the operation of subsystem 440 accounts for the movement of array 436 relative to platform 432 instead of the movement of platform 32 relative to array 36. System 420 can include one or more encoders (not shown) operatively coupled to subsystem 440 and/or other devices/techniques to track the position of array 436 relative to platform 432. System 420 can further include a communication subsystem (not shown) the same as subsystem 60 to remotely communicate with subsystem 440. Like previously described embodiments, system 420 is used to determine measurement, topographical, image, animation, and/or three-dimensional volume information about body B.

FIG. 8 illustrates electromagnetic radiation interrogation system 520 of yet another embodiment of the present invention. System 520 illuminates body B with selected electromagnetic radiation of the type previously described. For system 520, body B is in the form of person 522 wearing garments/clothing designated by reference numerals 524a and 524b. As in previously described embodiments, system 520 can be used to interrogate animate or inanimate objects.

System 520 includes scanning booth 530 coupled to control and processing subsystem 540. Scanning booth 530 includes frame 533 arranged to receive body B and support array 536. In contrast to the linear arrays 36 and 436 of previously described systems 20 and 420, array 532 is arranged as a ring or hoop generally centered with respect to centerline vertical axis V. A number of electromagnetic radiation transmitting/receiving elements are arranged in a generally circular pathway along the ring. These elements operate to interrogate body B with electromagnetic radiation including one or more wavelengths in the millimeter, microwave, and/or adjacent wavelength bands. Array 536 is arranged for translational movement along axis V to scan body B as represented by arrow T. One or more motors or other prime mover(s) (not shown) are utilized to selectively move array 536 along axis V.

Referring further to the partial top view of FIG. 9, array 536 is sized with opening 537 to receive body B there-through as array 536 moves up and down along axis V. In FIG. 9, axis V is generally perpendicular to the view plane and is represented by crosshairs. With the vertical motion of array 536, an imaginary cylinder is defined about body B in accordance with the circular path defined by the array ring; however, neither body B nor array 536 is rotated relative to the other, instead translational movement of array 536 is used to scan body B vertically.